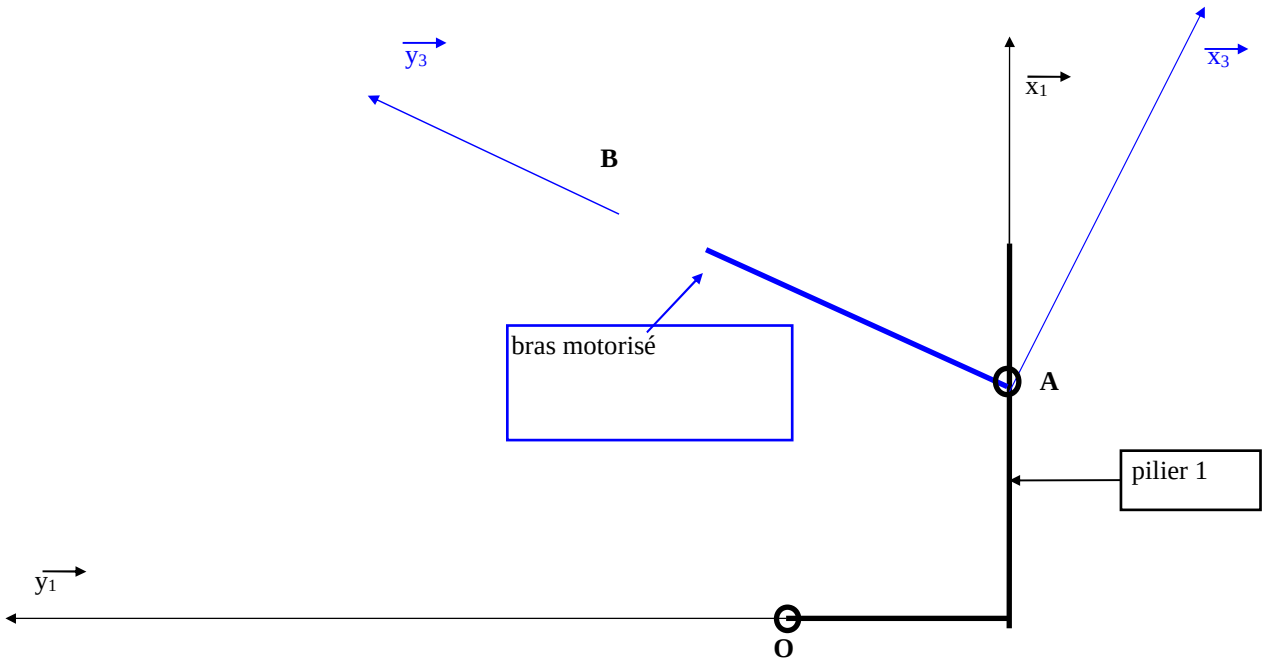
DR6_A3


$\overrightarrow{y_3}$
$\overrightarrow{x_1}$
$\overrightarrow{x_3}$
B
bras motorisé
A
pilier 1
$\overrightarrow{y_1}$
O